

IMSD-ACMD (Oct 16-20, 2022): Final Program (updated on Oct 15, 2022)

Time	Oct 16 (S)	Oct 17 (M)		Oct 18 (T)		Oct 19 (W)		Oct 20 (Th)
		Common		Common		Common		
		Track A (Lutyen's Lounge)	Track B (Viceroy's Hall)	Track A (Lutyen's Lounge)	Track B (Viceroy's Hall)	Track A (Lutyen's Lounge)	Track B (Viceroy's Hall)	Common
08:40 - 09:00		Inauguration						Social Program* 1. Depart Hotel Eros, New Delhi at 06:00 2. Visit Taj Mahal at Agra 3. Return to Delhi by 18:00
09:00 - 09:20		Keynote 1: Radu Serban Topic: Modeling and Simulation of Terramechanics and Vehicle-soil Interaction		Keynote 3: Shankar Venugopal Topic: A System dynamics approach to shaping future mobility technologies		Keynote 5: Etsujiro Imanishi Topic: Dynamics performance prediction on construction machinery		
09:20 - 09:40								
09:40 - 10:00								
10:00 - 10:20								
10:20 - 10:40								
10:40 - 11:00								
11:00 - 11:20								
11:20 - 11:40		Tea/Coffee		Tea/Coffee		Tea/Coffee		
11:40 - 12:00								
12:00 - 12:20								
12:20 - 12:40								
12:40 - 13:00								
13:00 - 13:20								
13:20 - 13:40		Lunch		Lunch		Lunch		
13:40 - 14:00								
14:00 - 14:20								
14:20 - 14:40		Keynote 2: Robert Seifried Topic: Servo-Constraints – An elegant way of inverting under-actuated and flexible multibody system models		Keynote 4: Alberto Cardona Topic: Simulation of wind turbines with full fluid/structure interaction and deforming blades				
14:40 - 15:00								
15:00 - 15:20								
15:20 - 15:40								
15:40 - 16:00								
16:00 - 16:20								
16:20 - 16:40		Industry Session**: FunctionBay (20 mins)						
16:40 - 17:00		Industry Session**: Solize & Hexagon (15 mins)						
17:00 - 17:20		Tea/Coffee		Tea/Coffee		Tea/Coffee		
17:20 - 17:40								
17:40 - 18:00	Terrace Garden	Lutyen's Lawns						
18:00 - 18:20		Banquet Dinner*						
18:20 - 18:40								
18:40 - 19:00	Registration and Welcome Reception							
19:00 - 19:20								
19:20 - 19:40								
19:40 - 20:00								

* Only for "Full" category registration and for those who have paid "Additional Fee for Taj Mahal visit" and/or "Additional Fee for Banquet"

** Venue for Keynote and industry sessions is Lutyens Lounge

Online participants
AT: Austria
CN: China
DE: Germany
ES: Spain
IN: India
JP: Japan
KR: South Korea
NL: Netherlands
US: United States

Session No	Code	Session Name
1	BIO	Biomechanics
2	APP	Applications, Multidisciplinary Methods, and Other Topics
3	BEN	Benchmark Problems in Multibody System Dynamics
4	COMP	Computational Methods and Real-Time Applications
5	CON	Contact, Impact, and Constraints
6	MEC	Control, Mechatronics, and Robotics
7	DYN	Dynamics of Vehicles
8	FLX	Flexible Multibody Systems
9	MOD	Modelling, Formalisms, and Theoretical Methods
10	MBD	Multibody Kinematics
11	SOC	MBD for Social Applications
12	OPT	Optimization, Sensitivity Analysis, and Parameter Identification

Paper ID	Session Code	Session Name	Paper Title	Presenting Author Name	Authors
11	SOC	MBD for Social Applications	Heads-up Display based on the Real-time Multibody Simulation of a Tractor	Suraj Jaiswal	Suraj Jaiswal, Rafael Aman, Jussi Sopanen, Aki Mikkola
15	OPT	Optimization, Sensitivity Analysis, and Parameter Identification	Application of Model Updating on the Numerical Model of a Classical Guitar with Identified Parameters from Experimental Modal Analysis	Pascal Ziegler	Alexander Brauchler, Pascal Ziegler, Peter Eberhard
16	BIO1	Biomechanics	Experimental biodynamic investigation on vibrational exposure of human body during a vehicle ride	Anirban Guha	Raj Desai, Anirban Guha, P. Seshu
17	MEC1	Control, Mechatronics, and Robotics	SAKSHAM: A WebGL/WebHID Based Framework for Creating a Digital Twin System for Virtual Robotics Labs	Arun Dayal Udai	Ashish Siddharth, Arun Udai
18	MEC1	Control, Mechatronics, and Robotics	Design and Control of All Pneumatic Virtual Motion Simulator	Ashish Siddharth	Arun Udai, Ashish Siddharth, Sourabh Khemka
22	MBD	Multibody Kinematics	Kinematic/Kinetic Formulation and Simulation Study for Hyper-Redundant Continuum Robot	Koichi Koganezawa	Azamat Yeshmukhametov, Yoshio Yamamoto, Koichi Koganezawa
23	SOC	MBD for Social Applications	Case study on fatigue damage due to dynamic effects in a revolute joint with clearance and wear	Javier Cuadrado	Manuel Ordiz, Javier Cuadrado, Mario Cabello, Iban Retolaza, Daniel Dopico
24	MOD1X	Modelling, Formalisms, and Theoretical Methods	Hybrid Dynamics for Closed-Loop Multibody Systems	Abhinandan Jain	Abhinandan Jain
25	FLX1	Flexible Multibody Systems	The Flexible Web Gear Modeling and Analysis Method for Efficient Gear Web Shape Design	Sunggyu Cho	Sunggyu Cho, Joonshik Yoon, Juhwan Choi, Jin-Gyun Kim, JIN HWAN CHOI
28	FLX2	Flexible Multibody Systems	Design Tools for Particle Dampers for Flexible Multibody Systems	Niklas Joachim Meyer	Niklas Meyer, Robert Seifried
29	MEC2	Control, Mechatronics, and Robotics	Sensorless force control with a Disturbance Observer for a compliant manipulator	Ronald Aarts	Ronald Aarts, Wouter Hakvoort
30	BEN	Benchmark Problems in Multibody System Dynamics	Monitoring Energy Errors in Explicit Co-Simulation Setups	Francisco J. González Varela	Borja Rodríguez, Alejandro Zar, Francisco Gonzalez, Miguel A. Naya, Javier Cuadrado
34	MOD1	Modelling, Formalisms, and Theoretical Methods	Estimation of Positional Error in Five-bar Manipulator under the Influence of Tolerances	Ankur Jaiswal	Ankur Jaiswal, H. P Jawale
42	APP1	Applications, Multidisciplinary Methods, and Other Topics	Contact analysis of slit at inlet of mobility device utilizing tether extension and winding	Satoshi Takayama	Satoshi Takayama, Shoichiro Takehara, KAZUKI NIRAYAMA
45	COMP2	Computational Methods and Real-Time Applications	A Study of Deep Neural Network based Data-driven Modeling for Real-time Flexible Multibody Dynamics Simulation	Seongji Han	Seongji Han, Hee-sun Choi, Juhwan Choi, JIN HWAN CHOI, Jin-Gyun Kim
54	MOD1	Modelling, Formalisms, and Theoretical Methods	DeNOC Based Dynamic Modelling Approach of Planar Closed Loop Robotic Mechanism	Rutupurna Choudhury	RUTUPURNA CHOUDHURY, Deep Singh, Yogesh Singh
66	COMP2	Computational Methods and Real-Time Applications	Synchronization and Scalability of the Multi-Agent Dynamics Environment SynChrono	Radu Serban	Jay Taves, Asher Elmquist, Alexandra Kissel, Radu Serban, Dan Negrut
67	BEN	Benchmark Problems in Multibody System Dynamics	Modelling and diagnosis of defects in spur gear under constant speed operation	Rajeev Kumar	Rajeev Kumar, Ranjan Gouda, Samrat Mandal, Chintamani Mishra
72	DYN1	Dynamics of Vehicles	Multibody model of railway wheelset using Natural Orthogonal Compliments	VISHNU SUKUMAR	S Vishnu, Satinder Paul Singh, Subir Kumar Saha
74	MBD	Multibody Kinematics	Determination of Point of Contact for Cone-Line and Cone-Cylinder Primitives using Denavit-Hartenberg (DH) Parameters	Rajeevlochana G Chittawadigi	Rajeevlochana Chittawadigi, Subir Kumar Saha
75	FLX2	Flexible Multibody Systems	A recursive simulation algorithm for soft robotics	Makoto Iwamura	Makoto Iwamura, Yoshiki Maeda, Kodai Ryomoto, Shunsuke Ide,
76	MEC2	Control, Mechatronics, and Robotics	Two-time Scale Control for Lane Keeping of 4WS Autonomous Ground Vehicles	Sayali Sunil Patil	Sayali Patil, Vijayraj Wanaskar, Pramod Shendge, Shrivijay Phadke
81	FLX2	Flexible Multibody Systems	Dynamics of Single-Link Flexible Manipulator: Theoretical and Experimental Study	Paramanand Nandihal	Paramanand Nandihal, Vikash Kumar, Sandeep Kumar, Subir Kumar Saha, Ashish Singla, Satinder Paul Singh, Tarun Kumar Bera
82	FLX3	Flexible Multibody Systems	Trajectory Control of Multi-Degree of Freedom Rigid and Flexible Manipulators	Satinder Paul Singh	Natraj Mishra, Satinder Paul Singh
83	BIO2	Biomechanics	An Equivalent Shoulder Model for Real-time Motion Capture and Reconstruction	Urbano Lugris	Urbano Lugris, Francisco Mouzo, Mario Lamas, Javier Cuadrado
85	APP1	Applications, Multidisciplinary Methods, and Other Topics	Validation of MBD-CFD Co-Simulation for Corrugating Machine	Rohit Arora	Rohit Arora, Atsushi Nakagawa, Tomoshige Takata, Tomohiro Akaki, Hiroyuki Kanazawa
87	FLX1	Flexible Multibody Systems	Modeling and Control of Shape Memory Alloy Spring Actuator in a Flexible Tube Manipulator	Nisha Bhatt	NISHA BHATT, Samyak Jain, vedanshu seedwan, Sanjeev soni, Ashish Singla

88	DYN1	Dynamics of Vehicles	Performance Evaluation of LuGre and Masing Models for Steering Torque Simulator	Taichi Shiiba	Taichi Shiiba, Shingo Haketa, Katsuhide Ishii, Sena Inoue
93	BIO1	Biomechanics	Multibody and Lumped-mass Modeling and Sensitivity Analysis	Hamid Lankarani	Jefferson Vieira, Luis Gomez-Valbuena, Gerardo Olivares, Hamid
96	CON	Contact, Impact, and Constraints	A note of controlled Rolling In-Hand Manipulation on Geodesic Curves	Rajesh Kumar	Rajesh Kumar, Sudipto Mukherjee
102	DYN2	Dynamics of Vehicles	Segment Based Modeling for Running Time Estimation of Rail Vehicles	Shashwat Jain	Shashwat Jain, Bhanu Vardhan Chennou, Vishnu S, Rajeevlochana G Chittawadigi, Subir Kumar Saha, Satinder Paul
103	SOC	MBD for Social Applications	Dynamic Analysis of the RuTAG Treadle Pump with Rocker-Link Mechanism	Suraj Bhat	Suraj Bhat, Subir Kumar Saha, Vinay Gupta
104	MBD	Multibody Kinematics	Modeling, simulation, optimization of the DLR Scout rover to enable extraterrestrial cave exploration	Antoine Pignede	Antoine F. X. Pignède, Roy Lichtenheldt
106	SOC	MBD for Social Applications	Mechanized Roller for Handmade Felt Making	vijay Saini	R. P. Saini, Sunil Kumar Singal, Vijay Saini, Yogeshwar Kumar,
110	BIO1	Biomechanics	Mobile Haptic Device for Large Virtual Environments	Abinaya P	Sasivarnan S K, Abinaya P, Prasanna Kumar Routray, Manivannan
111	MEC1	Control, Mechatronics, and Robotics	Design of Flexure Robotic Hand for Teleoperation	Shubham Bhandari	Mohd Zubair, Shubham Bhandari, Indranath Chatterjee
112	CON	Contact, Impact, and Constraints	DeNOC based recursive formulation to model ground impact of a biped	Alinjar Dan	Alinjar Dan, Subir Kumar Saha, Rama Krishna K
114	COMP1	Computational Methods and Real-Time Applications	Improved Graphical User Interface(GUI) of Recursive Dynamics Simulator (ReDySim) for Multibody systems	Suril Shah	Dinesh Kumar S, Alinjar Dan, Saurabh Chaudhary, Subir Kumar Saha, Suril Shah
118	MOD1X	Modelling, Formalisms, and Theoretical Methods	Effect of Orientation on the Collision-Free Printable Workspace of an Over-Constrained Cable-Driven Parallel Robot	Pushparaj Mani Pathak	Ishan Chawla, Pushparaj Mani Pathak
119	FLX2	Flexible Multibody Systems	Dynamic Analysis of Naturally Curved Rods using Cosserat Rod Theory	Sreejath S	Sreejath S, Subir Kumar Saha, Satinder Paul Singh
121	SOC	MBD for Social Applications	Preliminary Design of a new mechanism for Sheep Shearing Device	Rama Krishna K	Gunjan Mathur, Rama Krishna K, Subir Kumar Saha
125	MBD	Multibody Kinematics	Investigation of Indirect Force Control Strategies on Parallel Manipulator	Suril Shah	Akshay Goel, Suril Shah
130	BIO1	Biomechanics	Use of Inertial Measurement Units for Filter-tuning in Optical Motion Capture	Florian MICHAUD	Florian MICHAUD, Urbano Lugris, Manuel Perez-Soto, Javier Cuadrado
131	MOD1	Modelling, Formalisms, and Theoretical Methods	Review on Motion Planning of Space Robots	Prasad Dal	Prasad Dal, Suril Shah
132	BIO2	Biomechanics	Perception based Biomechanical Model Reduction for Needle Insertion Training Simulators	Ravali Gourishetti	Ravali Gourishetti, Manivannan Muniyandi
136	APP2	Applications, Multidisciplinary Methods, and Other Topics	Passive Gravity Compensation (PGC) of serial link manipulators for Remote Handling (RH) application	ManoahStephen Manuelraj	ManoahStephen Manuelraj, Ramasubramanian N
139	MEC1	Control, Mechatronics, and Robotics	Design and Development of a New Rotary Actuator based on Shape Memory Alloy and Permanent Magnet System	Rutupurna Choudhury	Deep Singh, RUTUPURNA CHOUDHURY, Yogesh Singh, Santhakumar Mohan
145	MOD1	Modelling, Formalisms, and Theoretical Methods	NOC based Dynamic Modelling of Multiphysics Systems: Studies on a DC Motor	Udayan Banerjee	Udayan Banerjee, Subir Kumar Saha, Indra Narayan Kar, Anirban Nag
149	MOD2	Modelling, Formalisms, and Theoretical Methods	Movement of a Bowed Subassembly Within a Fast Reactor Core cavity: A Multibody Dynamics Approach	VANDEEP GODHANI	VANDEEP GODHANI, R.SURESH KUMAR, SANJEEV KUMAR, JOSE VARGHESE, R Vijayashree
165	MBD	Multibody Kinematics	Investigation of the driving characteristics of electric bicycles by means of multi-body simulation	Johannes Bolk	Johannes Bolk, Burkhard Corves
166	DYN2	Dynamics of Vehicles	Estimating coach suspension parameters through stop braking: Analytical modeling and validation	Sudhir Kumar Singh	Sudhir Kumar Singh, Sanjay R. Singh, Vikranth Racherla
167	SOC	MBD for Social Applications	Multibody Dynamics Software-based simulation of a game for Robotics competitions	Sandeep Kumar	Sandeep Kumar, Subir Kumar Saha, Satinder Paul Singh
168	MEC2	Control, Mechatronics, and Robotics	Development of affordable Collaborative Robots for Engineering Education	Madhanagopal Manoharan	Ranga Rakesh Ranganayakulu, Sai Thilak Karanam Sreedhar, Aditya Navghare Shridhar, Madhanagopal Manoharan,
171	BEN	Benchmark Problems in Multibody System Dynamics	Non-linear Dynamic Analysis of Spur Gear pair with Rotor Bearing Clearances	Somnath Sarangi	Shubham Wasnik, Vikash Kumar, Shubhranshu Ranjan Sharma, Somnath Sarangi
173	COMP1	Computational Methods and Real-Time Applications	Multibody System Dynamics Simulation for Automotive Cyber-Physical Test Benches	Jon Garcia Urbieto	Jon García-Urbieto, Diego J. Palomar, Marta Marijuan, Borja Rodríguez, Francisco Gonzalez
175	APP1	Applications, Multidisciplinary Methods, and Other Topics	Multibody Dynamics study of Subassembly Transfer Flask under Seismic Excitation:	INAKOLLU SAI SASIDHAR	SASIDHAR INAKOLLU, SAJISH S.D., JOSE VARGHESE

176	APP3	Applications, Multidisciplinary Methods, and Other Topics	Modified Lagrangian Formulation of Gear Tooth Crack Analysis using Combined Approach of Variable Mode Decomposition (VMD) – Time Synchronous Averaging (TSA)	Subrata Mukherjee	Subrata Mukherjee, Vikash Kumar, Somnath Sarangi
177	COMP2	Computational Methods and Real-Time Applications	Comparison of Integration Methods for Real-Time Capable Multibody Simulation of an Elastokinematic Wheel Suspension System	Jan-Lukas Archut	Jan-Lukas Archut, Burkhard Corves
179	FLX1	Flexible Multibody Systems	A study of Harmonic drive nonlinear torsion stiffness based on flexible multi-body dynamics simulation	Seok Hee Han	SeokHee Han, Joonho Lee, Jonghyeon Sohn, Byung-Kil Han, Joo-Hong Lee, Dongll Park, Jin-Gyun Kim
180	OPT	Optimization, Sensitivity Analysis, and Parameter Identification	Innovative two-axle vehicle with improved ride comfort via blended active vibration control	Rocco Libero Giossi	Rocco Libero Giossi, Rickard Persson, Sebastian Stichel
181	DYN2	Dynamics of Vehicles	Simulation based Risk Analysis of Autonomous Emergency Braking System Test Scenario Using Analytic Hierarchy Process Method	Sheng-peng Zhang	Shengpeng Zhang, Jiyeon Choi, Donghoe Heo, Jongmin Baek, Yeongseo Park, Taeoh Tak
182	COMP2	Computational Methods and Real-Time Applications	Hardware-in-the-loop Simulator of Hydraulic Manipulator System for Decommissioning Nuclear Power Plant	MyoungHo Kim	MyoungHo Kim, Sung-Soo Kim, Sung-Uk Lee
183	CON	Contact, Impact, and Constraints	Numerical Considerations for Simulating Wear in Revolute Joints	Mario López-Lombartero	Mario López Lombartero, Javier Cuadrado, Mario Cabello, Félix Martínez
184	APP2	Applications, Multidisciplinary Methods, and Other Topics	Kalman Filters Based on Multibody Models with Colored Noise	Antonio J. Rodríguez	Antonio J. Rodríguez, Emilio Sanjurjo, Miguel A. Naya
186	BIO1	Biomechanics	Estimating Double-stance Ground Reaction Forces and Moments From Motion Capture Data Without Using Force Plate Measurements	Behzad Danaei	Behzad Danaei, John McPhee
188	MEC2	Control, Mechatronics, and Robotics	Approaches for Feedforward Control of Flexible Multibody Systems Modeled by the ANCF	Svenja Drücker	Svenja Drücker, Robert Seifried
189	MBD	Multibody Kinematics	Multibody Constrained Dynamic Modelling of Human-Exoskeleton: Toward Optimal Design and Control of an Active-passive Wearable Robot	Ali Nasr	Ali Nasr, John McPhee
190	DYN1	Dynamics of Vehicles	Enhanced Hierarchical Multiscale Modeling for Off-Road Mobility Simulation with Neural Network Surrogate Model	Hiroyuki Sugiyama	Guanchu Chen, Hiroki Yamashita, Yeefeng Ruan, Paramsothy Jayakumar, Kenneth Leiter, Jaroslav Knap, Xiaobo Yang, Hiroyuki
191	MEC1	Control, Mechatronics, and Robotics	Fabrication and Stabilization of Rotary Inverted Pendulum Setup using a PID Controller (STRIPS 1.0)	Tufail Ahmad Bhat	Tufail Ahmad Bhat, Dr. Majid Hameed Koul
192	APP1	Applications, Multidisciplinary Methods, and Other Topics	Aerial Transportation and Manipulation of a Cable-Slung Payload with Decentralized Swarm Agents	Aniket R Sharma	Aniket Sharma, Nandan Sinha
193	FLX2	Flexible Multibody Systems	A Unified Framework for Linearly-Elastic Flexible Multibody System Dynamics Formulations	Andreas Zwölfer	Andreas Zwölfer, Johannes Gerstmayr
194	FLX1	Flexible Multibody Systems	Flexible Rotating Multibody Analysis Using Extended NPFEM for Non-Equatorial Space Elevator	Ryo Kuzuno	Ryo Kuzuno, Shuonan Dong, Yuya Takahashi, Taiki Okada, Yoshitaka Shizuno, Keisuke Otsuka, Kanjuro Makihara
195	MOD1	Modelling, Formalisms, and Theoretical Methods	Mechanics of Flexible Bodies in Local Orthonormal Frames	Valentin Sonneville	Valentin Sonneville, Michel Géradin
197	COMP2	Computational Methods and Real-Time Applications	Digital Twin Model of Marine Robot using Recursive Subsystem Synthesis Method	Sung-Soo Kim	Sung-Soo Kim, Chang-Ho Lee, Jong-Boo Han
198	DYN1	Dynamics of Vehicles	Estimation of Wheelset Equivalent Conicity using the Dual Extended Kalman Filter	Prapanpong Damsongsaeng	Prapanpong Damsongsaeng, Rickard Persson, SEBASTIAN STICHEL, Carlos Casanueva
199	COMP1	Computational Methods and Real-Time Applications	Exudyn - A C++ based Python package for flexible multibody systems	Johannes Gerstmayr	Johannes Gerstmayr
200	CON	Contact, Impact, and Constraints	A Study on Contact Behavior of ANCF Flexible Beams	Ken Suzuki	Ken Suzuki, Yoshiki Sugawara, Masakazu Takeda
201	CON	Contact, Impact, and Constraints	A dynamic friction model with normal force and coefficients of friction as parameters of transition range	Jyotirmoy Mukherjee	Ekansh Chaturvedi, Jyotirmoy Mukherjee, Corina Sandu
203	OPT	Optimization, Sensitivity Analysis, and Parameter Identification	Sensitivity analysis of semi-recursive augmented Lagrangian formulations with projections	Álvaro López Varela	Álvaro López Varela, Daniel Dopico, Alberto Luaces
204	APP2	Applications, Multidisciplinary Methods, and Other Topics	A linear frequency domain solver workflow for fast simulation of transmission systems	Josef Haslinger	Josef Haslinger, Klaus-Dieter Bauer, Günter Offner

205	FLX3	Flexible Multibody Systems	Formation of a wide low frequency attenuation bandgap in a mass-in-mass frictional metamaterial	Muskaan Sethi	Muskaan Sethi, ARNAB BANERJEE, Bappaditya Manna
207	MOD2	Modelling, Formalisms, and Theoretical Methods	Dynamic behavior of planetary spur gear train affected by tooth clearance and manufacturing deviations based on Jacobian-torsor deviation model	Haidong Yu	Zikang Xia, Haidong Yu, Bin Gu, Hao Wang
209	FLX1	Flexible Multibody Systems	Command Shaped Trajectory Tracking Control for a Two-link Flexible Manipulator	Ashish Singla	Sandeep Kumar, Subir Kumar Saha, Ashish Singla, Satinder Paul Singh, Tarun Kumar Bera
210	DYN2	Dynamics of Vehicles	Dynamics of moving load on simply-supported beam using sprung-mass model	Susmita Panda	Susmita Panda, Arnab Banerjee, Bappaditya Manna
211	CON	Contact, Impact, and Constraints	A 2D Unified Gait Model for both single and double stances	ABHYUDIT SINGH MANHAS	ABHYUDIT SINGH MANHAS, Sourav Rakshit
214	APP2	Applications, Multidisciplinary Methods, and Other Topics	Soft robotic prosthetic hand based on Fin Ray effect	Banibrata Datta	Sekar Anup Chander, Banibrata Datta, Srikanth Vasamsetti, MD Sameer, Akshit Gupta, P S Suvin
215	APP2	Applications, Multidisciplinary Methods, and Other Topics	Finite Element Analysis to Study the Effect of Tool Deflection in Incremental Forming Process	ELDHO PAUL	ELDHO PAUL, Hariharan Krishnaswamy, Riby A Bobby, Sahil Bharti
216	BIO2	Biomechanics	Optimal trajectory stabilization of lower limb exoskeleton involving hybrid contact dynamics	Mowbray RV	Mowbray RV, Sourav Rakshit
219	BEN	Benchmark Problems in Multibody System Dynamics	Modeling and Validation of Human Gait Dynamics using Modified Euler-Lagrange Approach	Sekar Anup Chander	sekar anup chander, Ashutosh Mukherjee, Vhatkar Dattatraya Shivling, Ashish Singla
220	MEC2	Control, Mechatronics, and Robotics	UAV Landing on General Moving Platforms Without Markers	Kaushal Kishore	Sagar Dalai, Kanishk Vishwakarma, Kaushal Kishore, Dhruv Potdar, Manan Arora
221	MOD1	Modelling, Formalisms, and Theoretical Methods	Modelling of 12-DoF Parachute – Riser – Payload System Dynamics using Kane's method	Prashant G. Iyer	Prashant Iyer
222	OPT	Optimization, Sensitivity Analysis, and Parameter Identification	Optimal design and control of the steering of a tilting tricycle	Daniel Dopico	Alberto Luaces, Álvaro López Varela, Adwait Verulkar, Corina Sandu, Adrian Sandu, Daniel Dopico
223	DYN2	Dynamics of Vehicles	Application of an iterative rheo-linear frequency domain solver to unbalance effects of transmission systems	Klaus-Dieter Bauer	Klaus-Dieter Bauer, Josef Haslinger, Günter Offner
224	DYN1	Dynamics of Vehicles	Breaking simulation of railway vehicle under low friction coefficient conditions considering wheel slide re-adhesion control	Sora Sakanishi	Sora Sakanishi, Shihpin LIN, YOSHIHIRO SUDA
226	APP3	Applications, Multidisciplinary Methods, and Other Topics	Multi-body Dynamic Analysis of Ammunition Transfer and Ramming Mechanisms in the Autoloader of Military Tracked Vehicle	YATESH KUMAR SINGH	Y.K Singh, S. Dev Anandh, Sunny Kumar, S Banerjee, G Srinivasan, N Babu
227	APP1	Applications, Multidisciplinary Methods, and Other Topics	Digital Twin for the Condition Monitoring of Railway Bogies Based on Multibody Dynamics Tools	Jorge Ambrósio	Jorge Ambrósio, João Pagaimo, Pedro Millan, João Costa